



Netherlands Enterprise Agency



Ministry of Housing and Spatial
Planning

kadaster



National Institute for Public Health
and the Environment
Ministry of Health, Welfare and Sport



het Waterschapshuis

✖ Gemeente
✖ Amsterdam
✖



Gemeente Utrecht

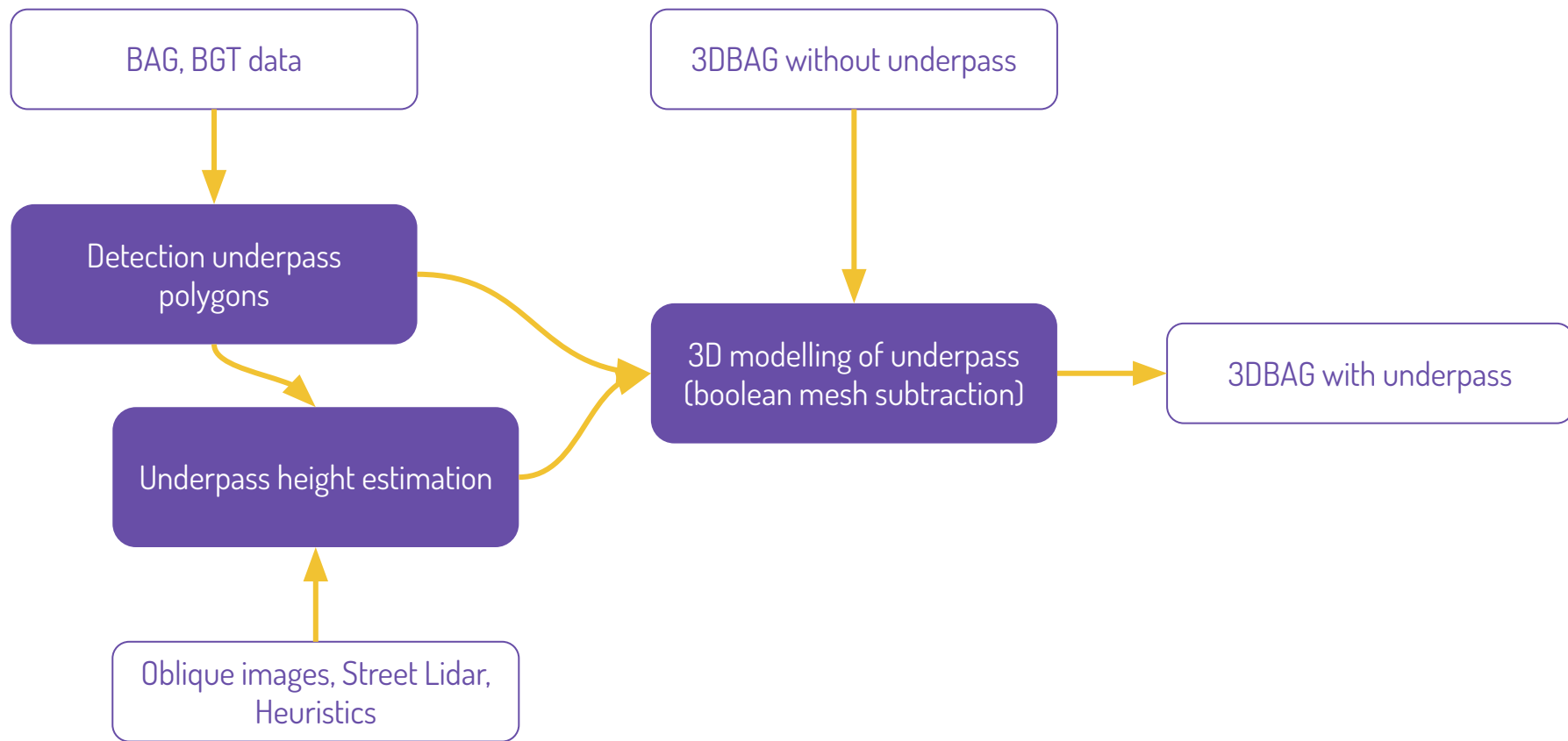


Innovatieve algoritmes voor betrouwbare, stedelijke 3D-modellen

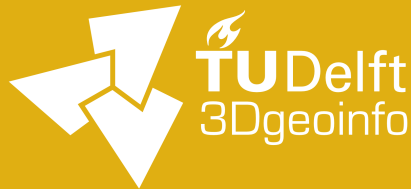
Update, 19 Januari 2026
Online



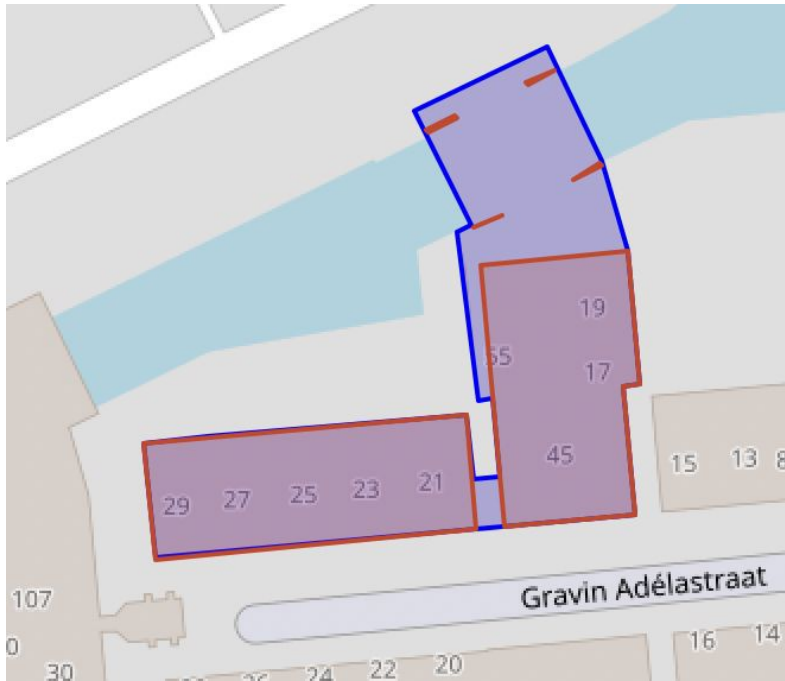
Overview technical components



Detection of Underpass Polygons



Methodology



BAG - BGT



Underpasses

Detection in Rotterdam



Next step: detect type of underpass (semantic enrichment)

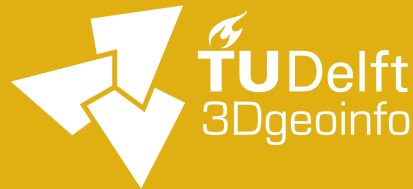


**Pedestrian path
through buildings**



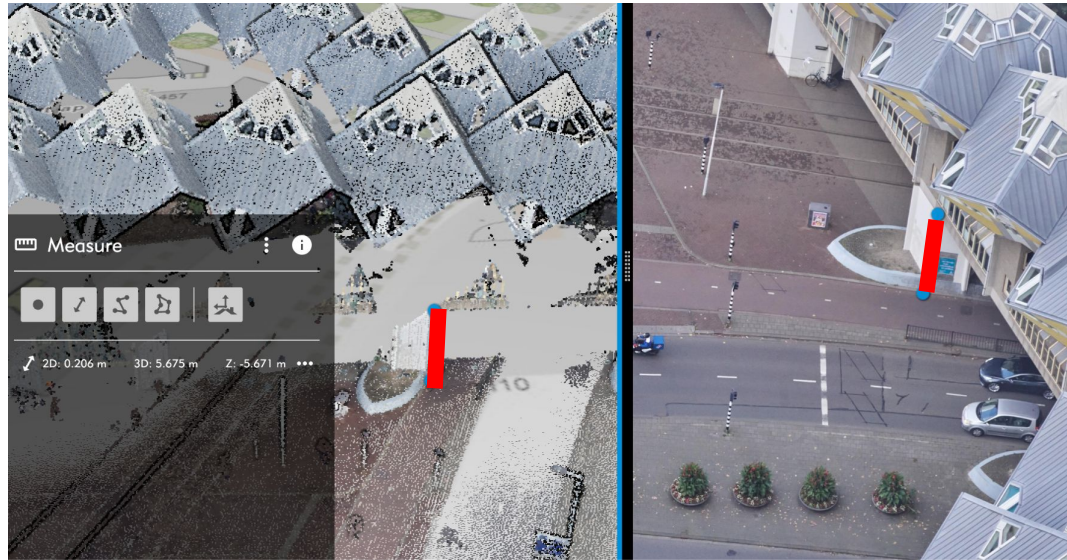
Car access

Underpass Height Estimation



Underpass Height Estimation

Oblique Aerial Images



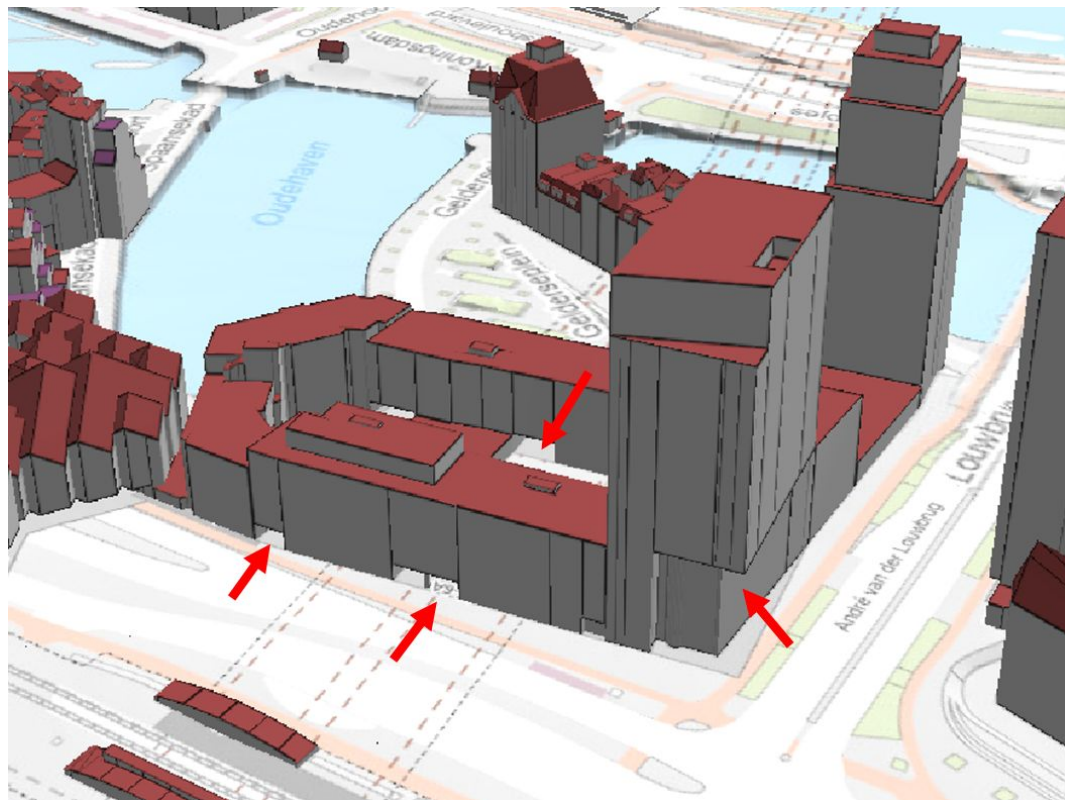
SpoorInBeeld, ProRail

Lidar

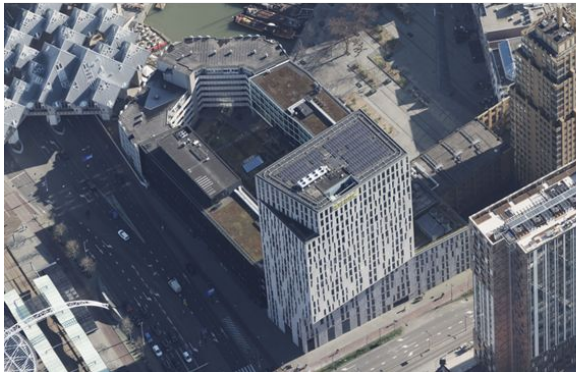


AHN5

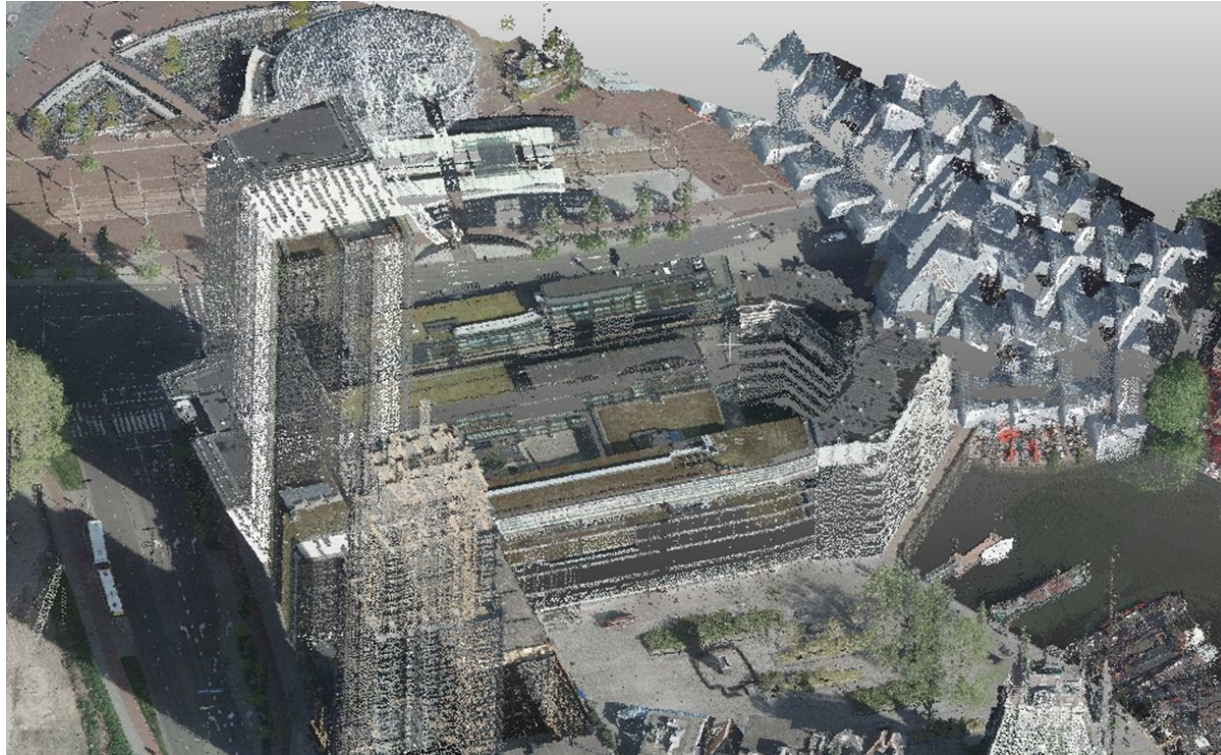
Geldersplein 50 - Rotterdam



Geldersplein 50 - Rotterdam



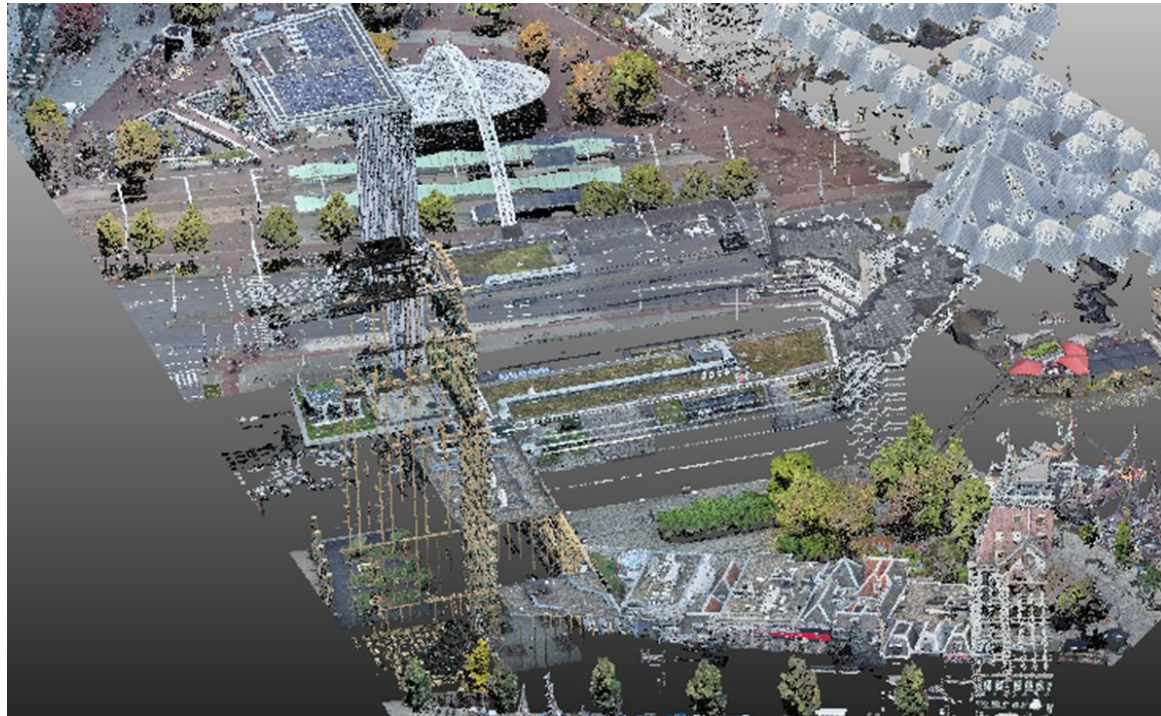
Geldersplein 50 - Rotterdam



Geldersplein 50 - Rotterdam



Geldersplein 50 - Rotterdam



Beemsterstraat 42 - Amsterdam



Municipality data

Beemsterstraat 42 - Amsterdam

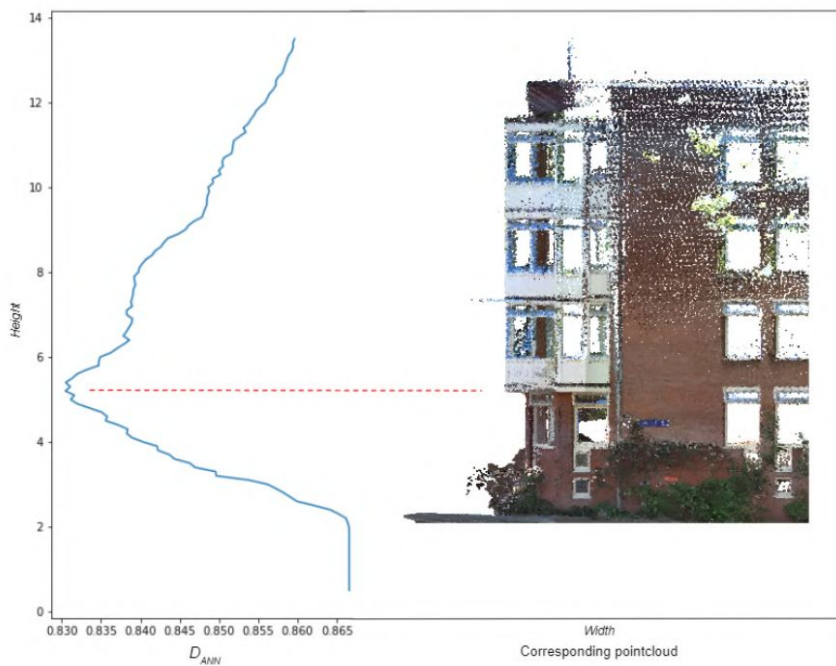


Municipality data

Beemsterstraat 42 - Amsterdam



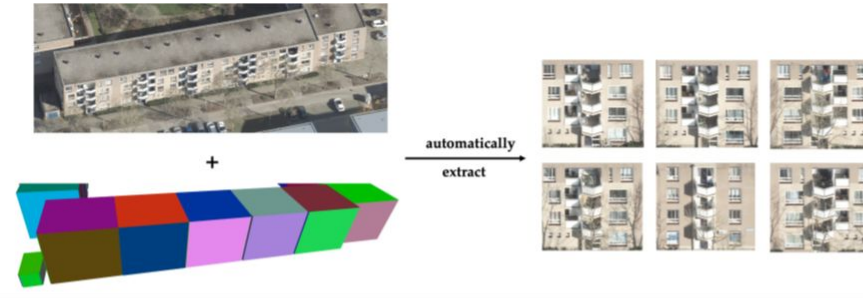
Approach 1 - using point cloud data



1. Sample points from already existing 2.5D model (3DBAG) $\rightarrow$ set $\mathbf{M}$
2. Extrude 2D polygon and sample points $\rightarrow$ set $\mathbf{N}$
3. Compute intersection of $\mathbf{M}$ and $\mathbf{N}$ at different heights $\rightarrow$ Candidate model
4. Compare each candidate model to real point cloud. Estimate height based on similarity with real point cloud

Augmented and Guided City-Scale Facade Reconstruction using Terrestrial Point Clouds and Prior Building Knowledge (Bob Leijnse, 2022)

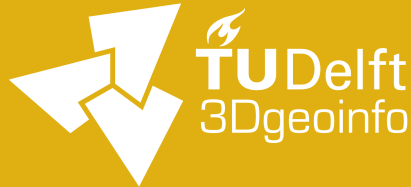
Approach 2 - using oblique imagery



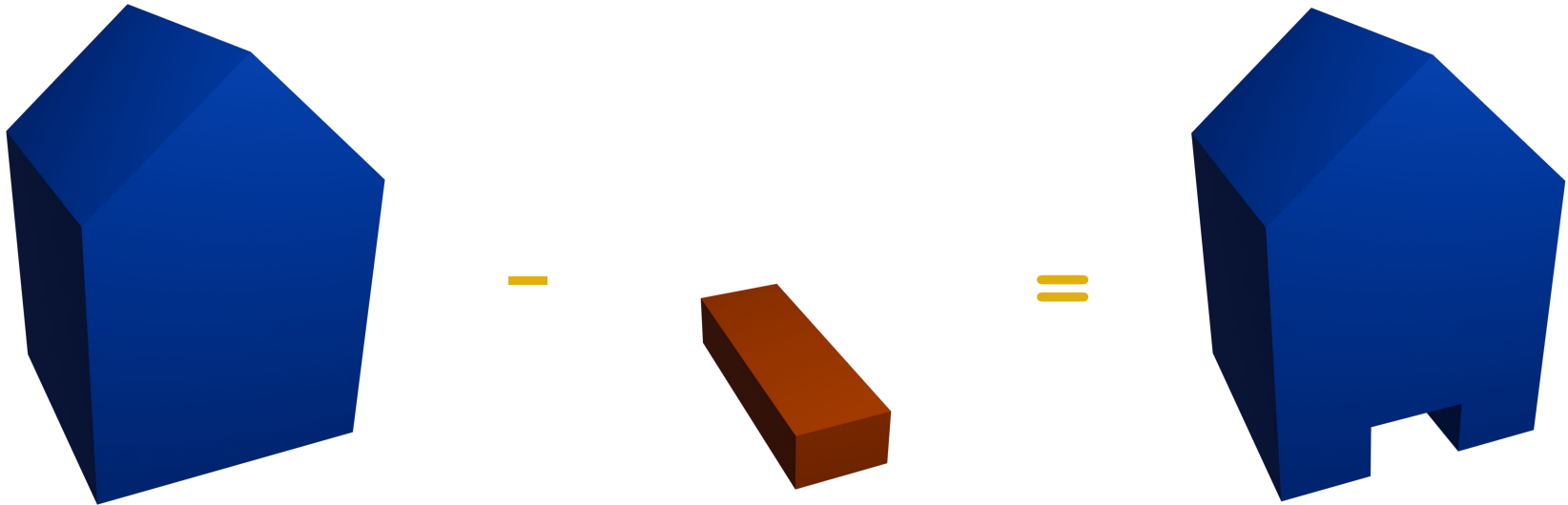
1. Project 3D facade on oblique images → extract facade region
2. Adjust projection → straighten facade
3. Detect underpass
4. Estimate height

A data-driven approach to add openings to 3D BAG building models (Y. Xia, 2023)

3D modelling of underpass (boolean mesh subtraction)



3D modelling of underpass (boolean mesh subtraction)

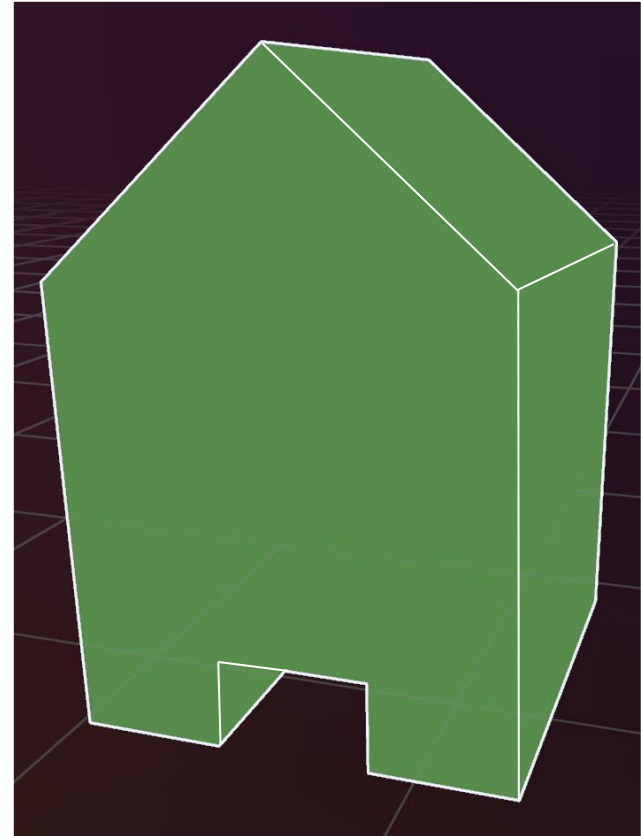
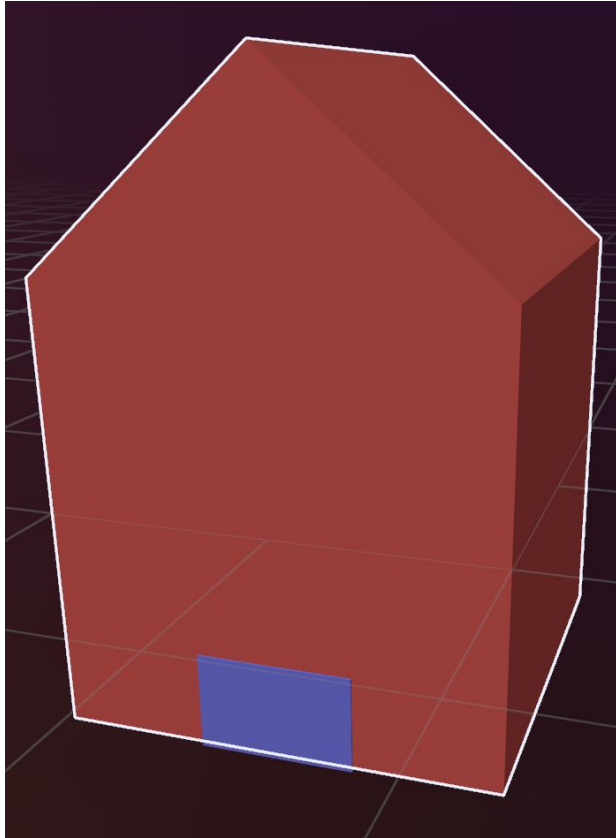


Handmatig gegenereerd

3D modelling of underpass (boolean mesh subtraction)

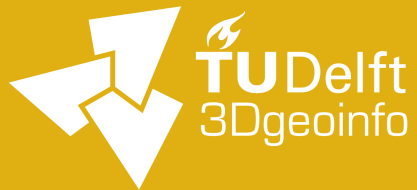
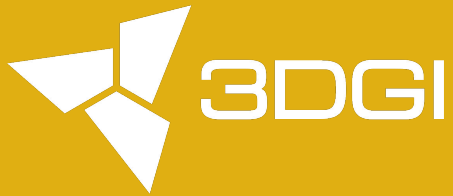
- 3 kandidaat software bibliotheken: *CGAL*, *geogram*, *manifold*
- Begonnen met eerste implementatie op basis van *manifold* en simpele data
- Volgende stappen:
 - Inlezen van 3DBAG model + polygoon onderdoorgang met hoogte
 - Implementatie andere kandidaten
 - vergelijking van 3 kandidaten voor groter testgebied op
 - snelheid
 - kwaliteit
 - betrouwbaarheid

3D modelling of underpass (boolean mesh subtraction)



Automatisch gegenereerd

Use cases



Use cases: aanvullingen, illustraties?

1. Visualisatie & participatie

- realistischer stadsmodellen voor communicatie met bewoners en stakeholders.=

2. Mobiliteit, bereikbaarheid/veiligheid

- vluchtroutes, doorstroom- en crowd management (event/gebied).
- verkeersstromen door gebouwencomplexen (overkluizingen/kubuswoningen Rotterdam).

3. Energie, klimaat, omgeving

- compactheid, schaduw/koelte-routes (hittestress), potentiële input voor warmteverlies-/windsimulaties. Urban heat island
- Geluidsimulatie
- Overstroming
- (Modelling stables for animals, estimating how many cattle)

4. Innovatie potentieel

- Bruggen: vergelijkbare problematiek (hoogte-invulling waar data ontbreekt); mogelijk hergebruik heuristieken.
- Viaducten
- Aantonen nut van bv oblieke beelden, aanmoedigen nationale inwinning.



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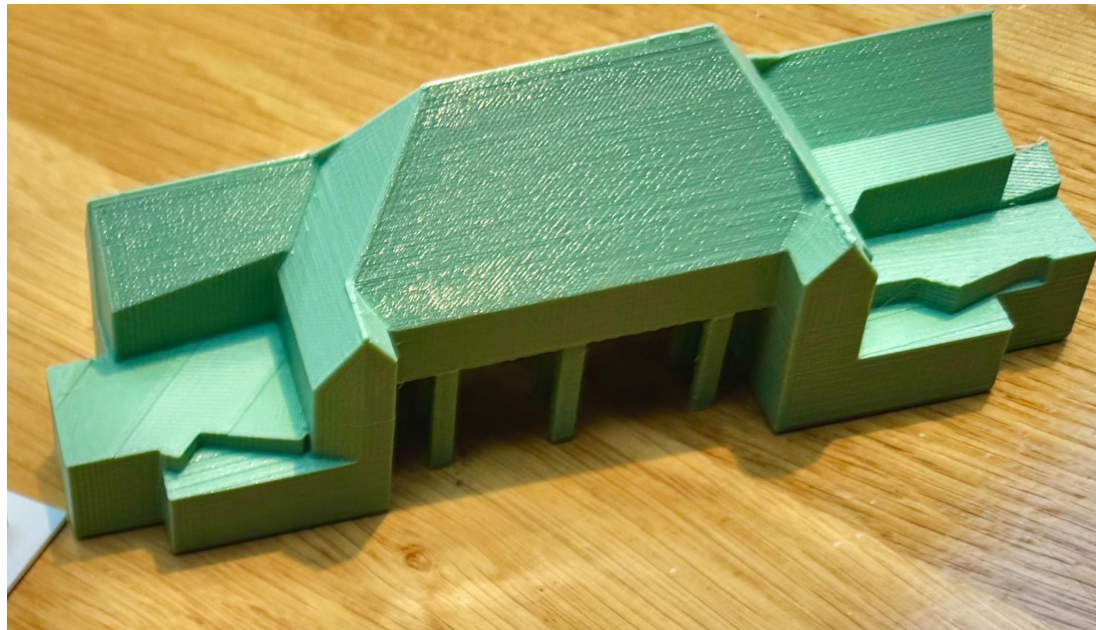


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✖ Amsterdam
✖

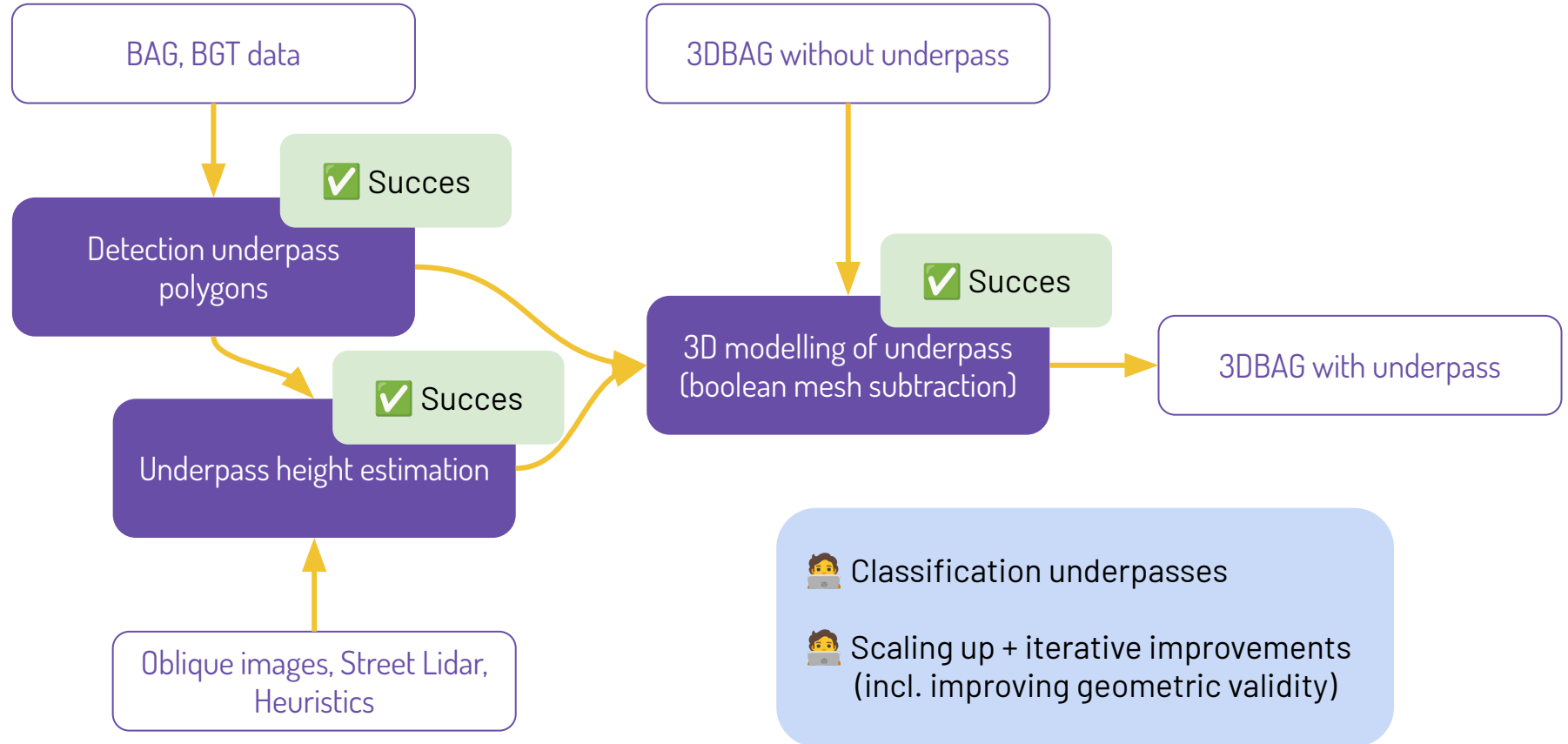


Innovatieve algoritmes voor betrouwbare, stedelijke 3D-modellen

Update, 16 maart 2026
Online



Status update



Classification of Underpasses (semantic enrichment)

Type classification



Arcade



Pedestrian path through buildings



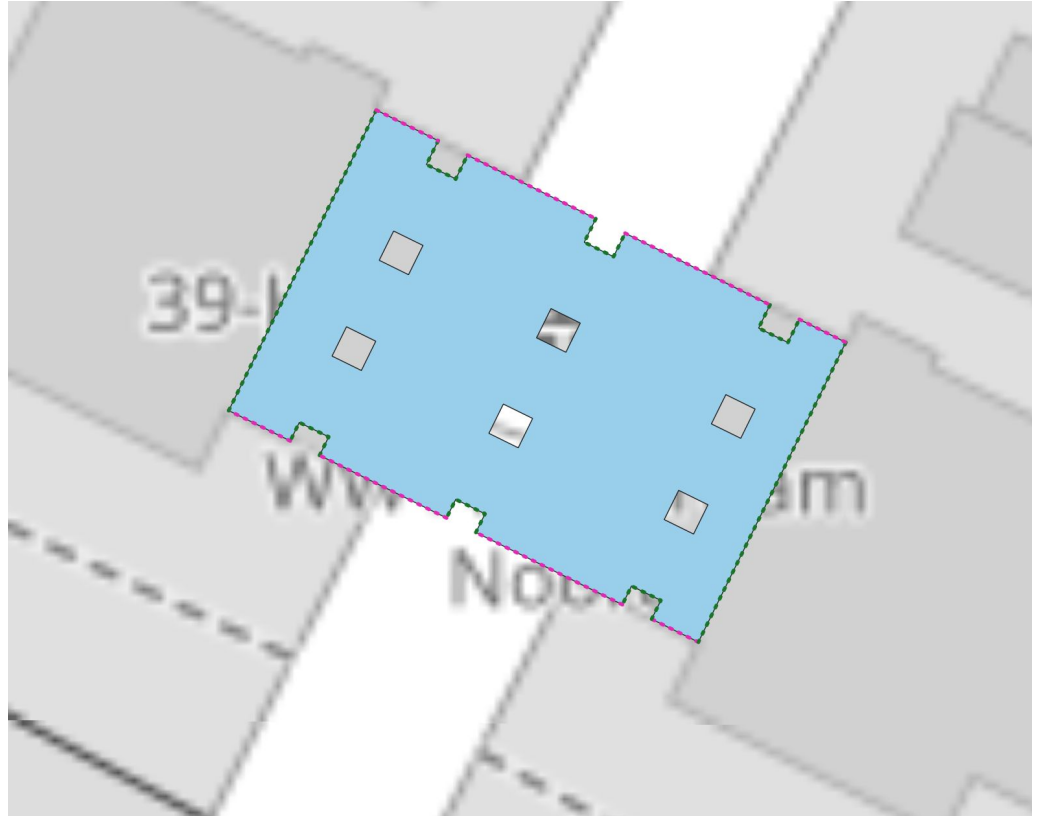
Pass-through with car access

**Important for
Disaster
Management**

Type classification

Topological classification
based on the edges of the
detected underpass:

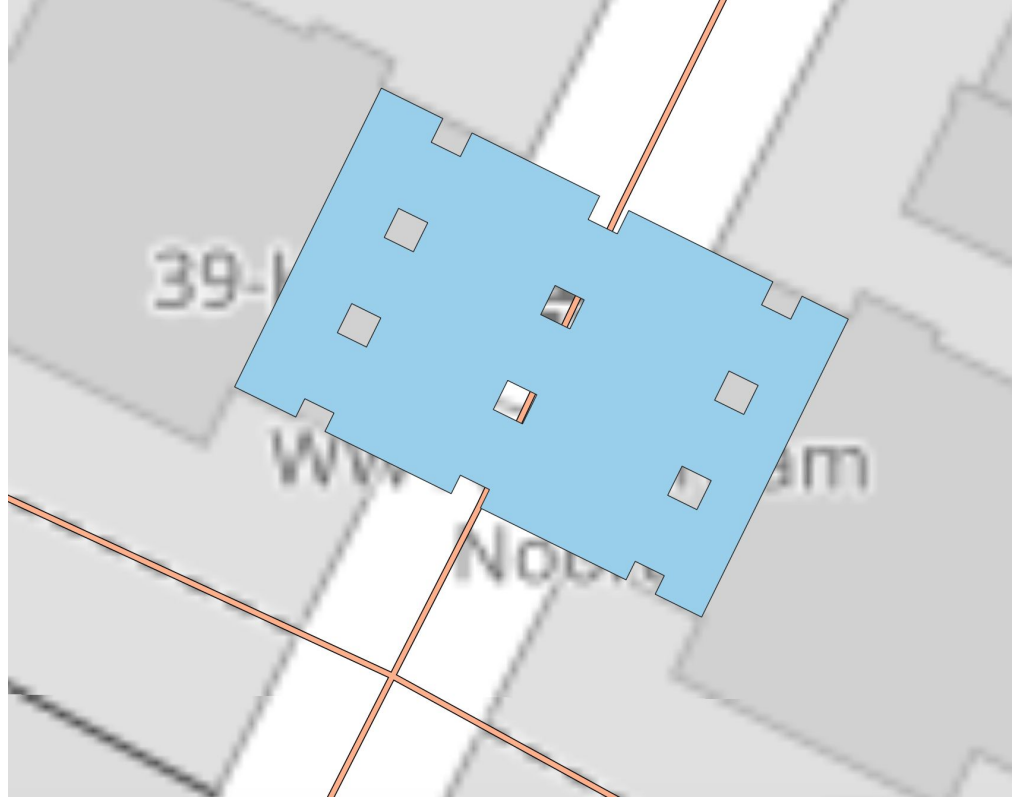
If the underpass has more than
one exterior edge (eg exit) then
it is a “pass-through”
underpass.



Type classification

Accessibility classification
based on intersections with
road network:

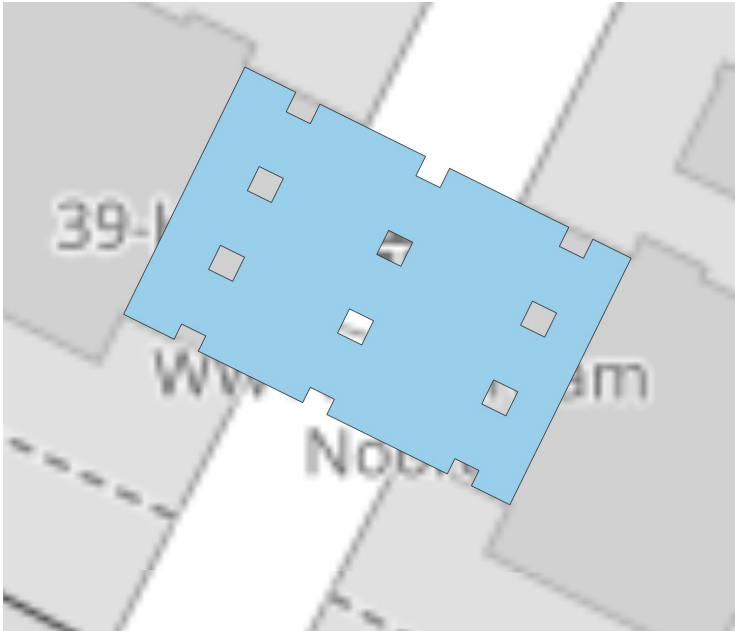
If the underpass intersects
with road segments the it is
classified as " car accessible"
otherwise "pedestrian-only".



Type classification

Beemsterstraat 42

**A "car-accessible,
pass-through"**



Type classification

Weesperstraat 430

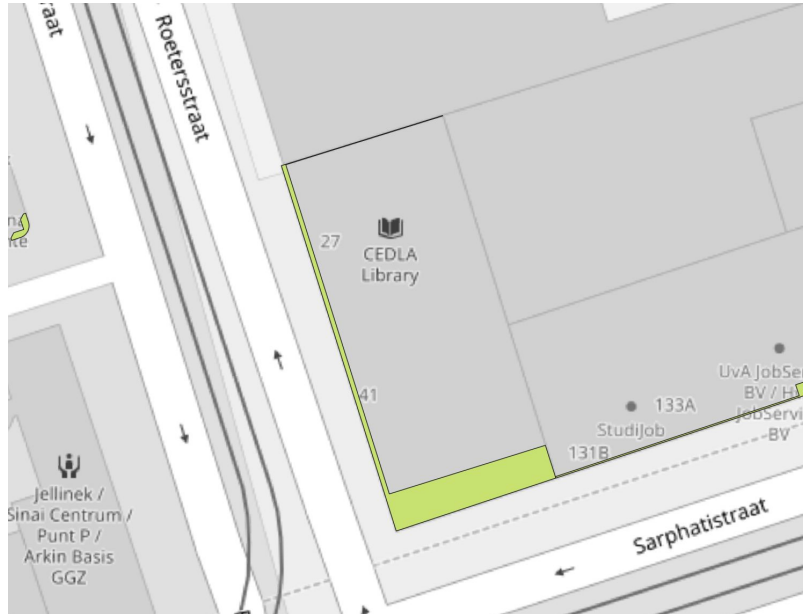
**A “pedestrian-only,
pass-through”**



Type classification

Sarphatistraat 129

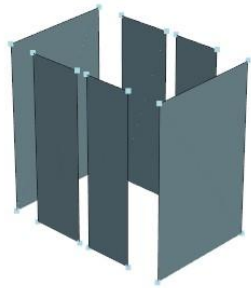
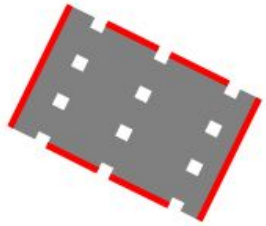
An “arcade, pedestrian-only”



Hoogtebepaling uit oblique
luchtfoto

Beemsterstraat

Perspective projection



Beemsterstraat

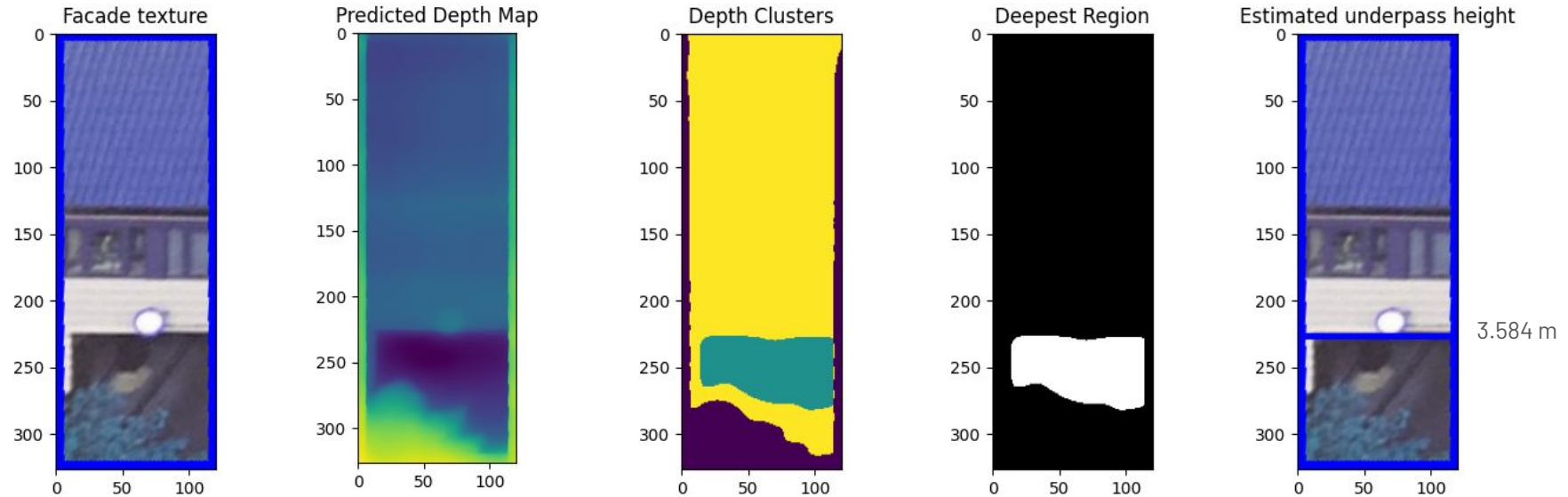
Perspective projection

- Highly reliable in camera parameters accuracy



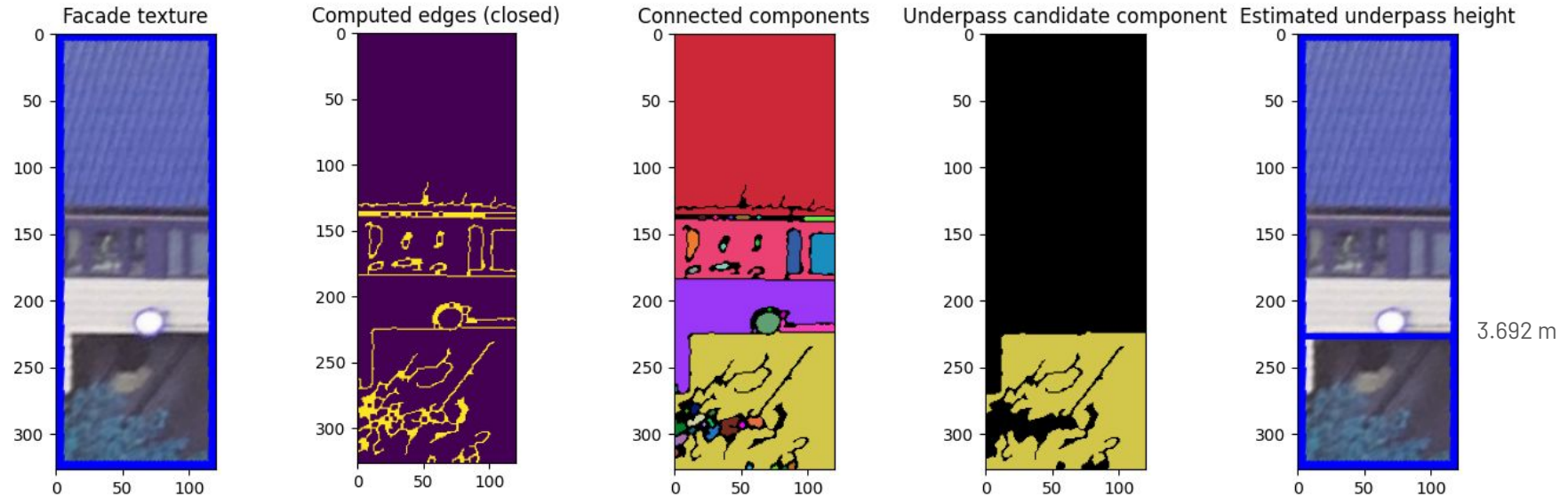
Beemsterstraat

Depth Map Method



Beemsterstraat

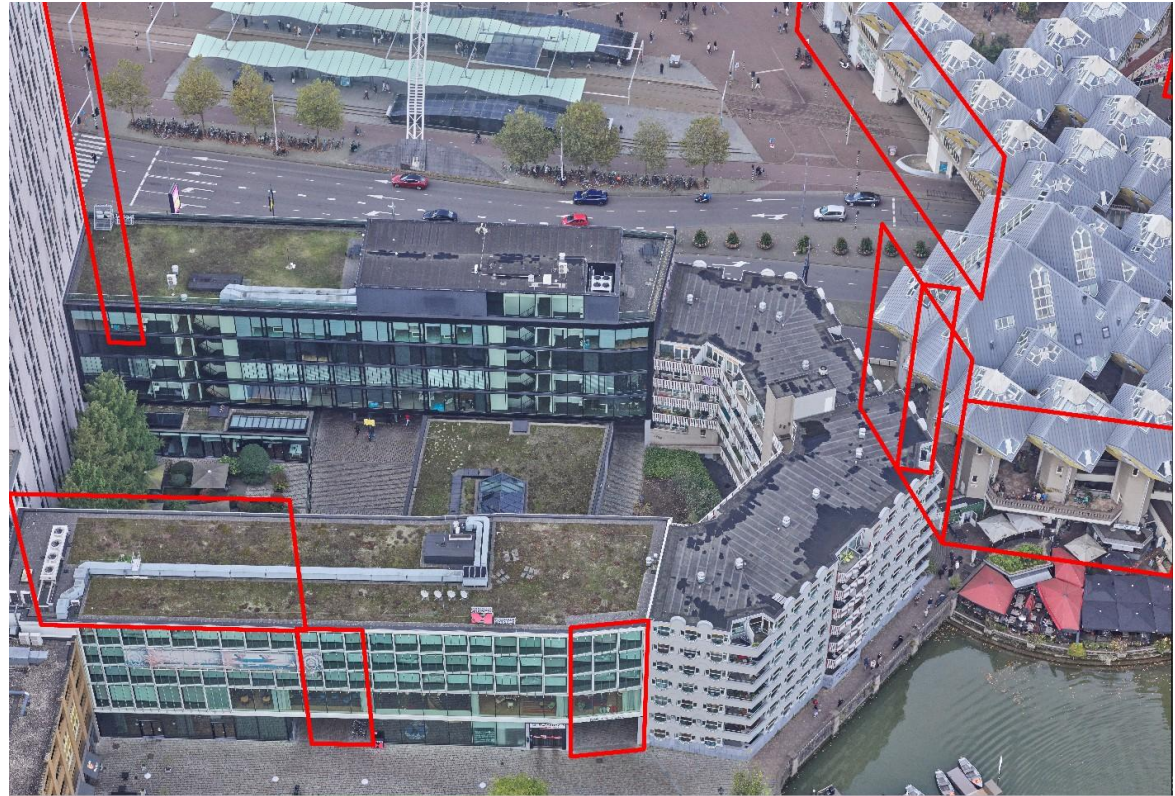
Connected Components Method



Gelderseplein

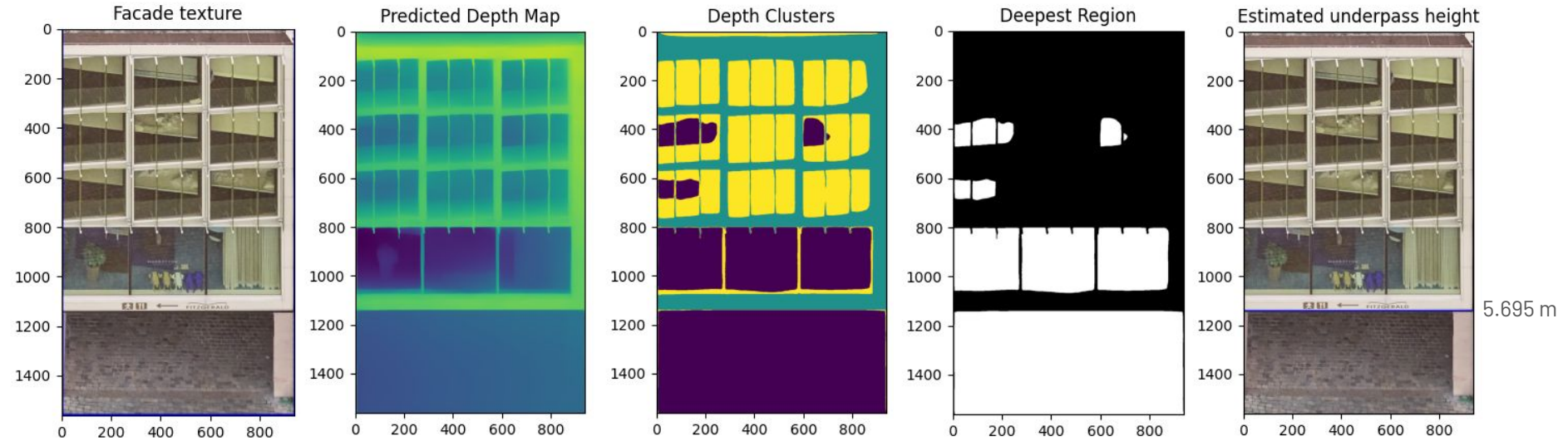
Perspective projection

- ProRail data



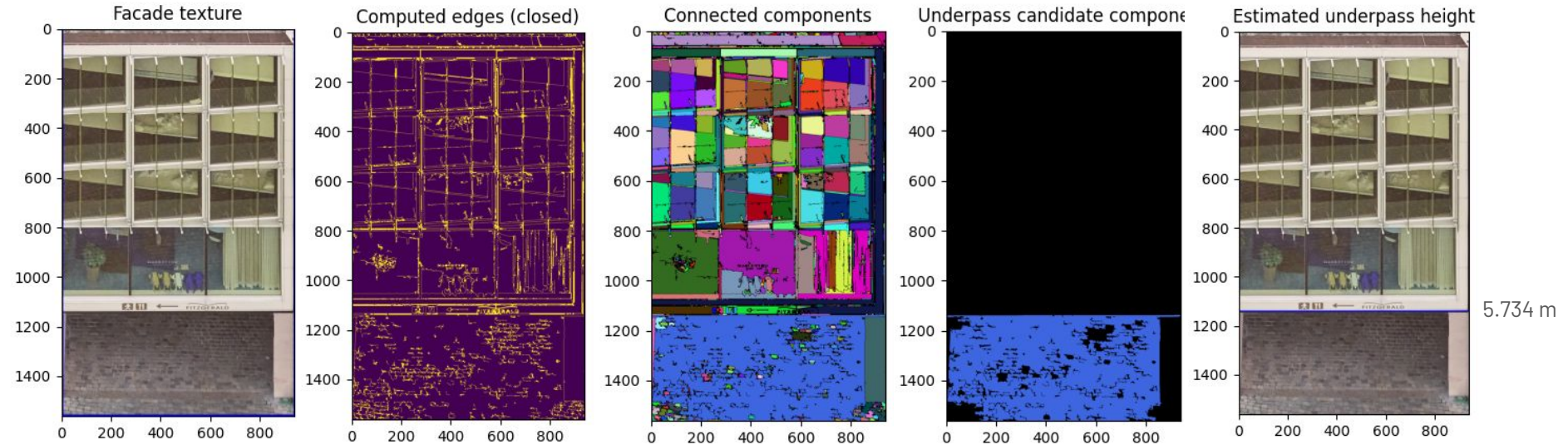
Gelderseplein

Depth map method

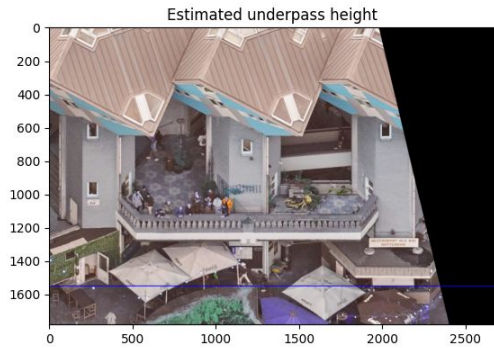


Gelderseplein

Connected components method



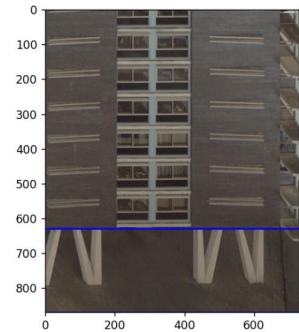
Challenges



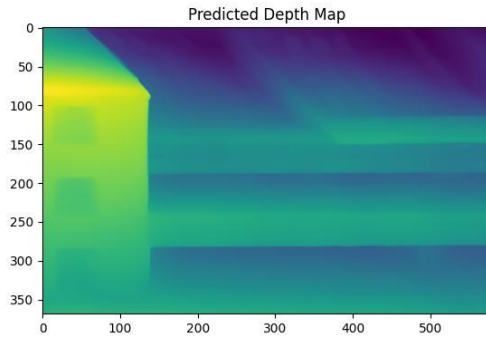
Presence of city objects



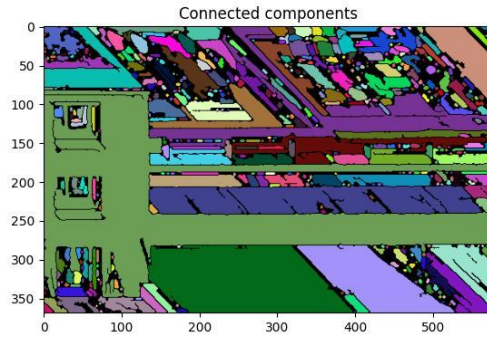
Extraction of wrong images



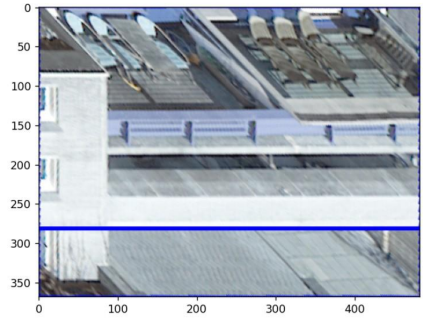
Facade misalignments
(Projection inaccuracies)



Computationally heavy



No semantic understanding



Vertical distortions

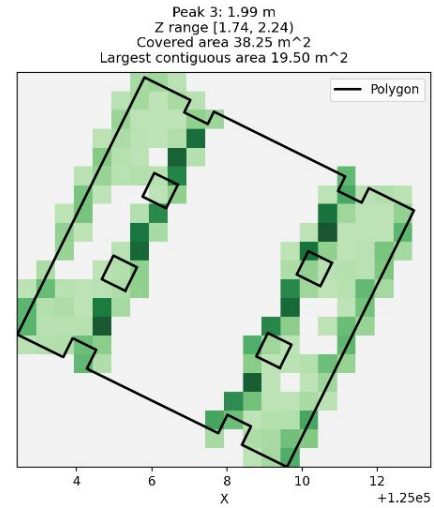
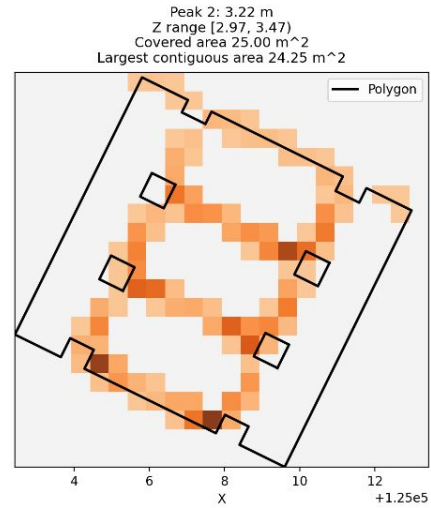
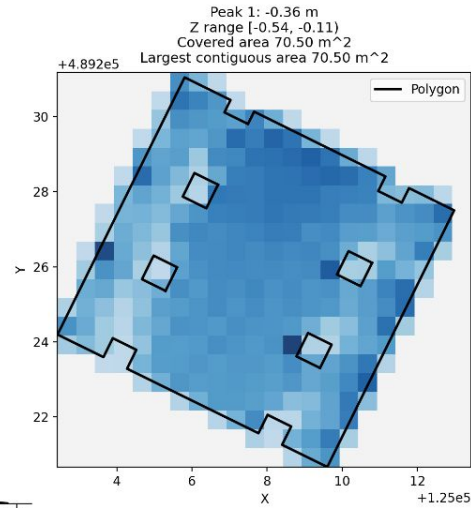
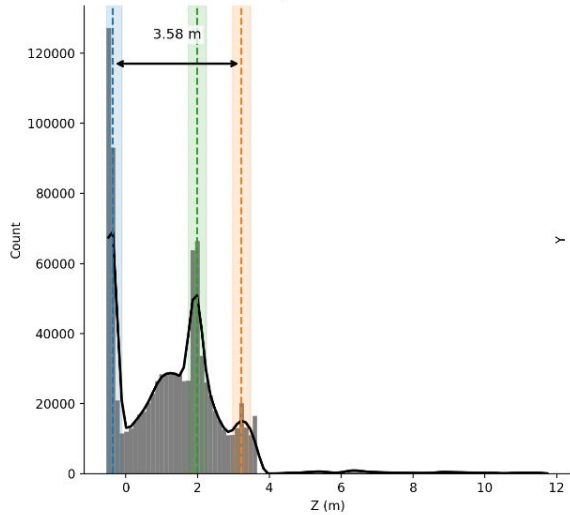
Hoogtebepaling uit streetview Lidar

Beemsterstraat

NL.IMBAG.Pand.0363100012095711

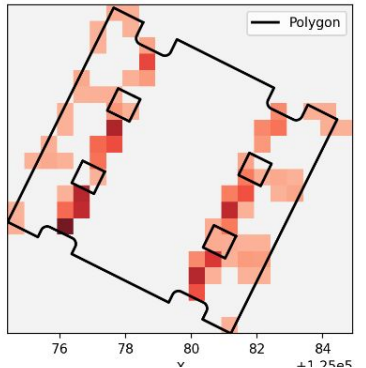
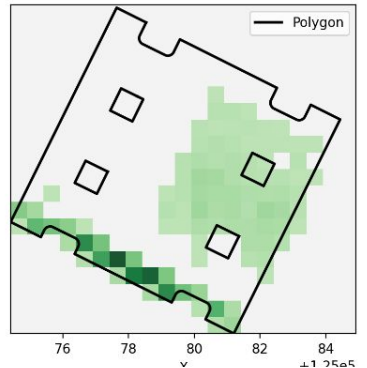
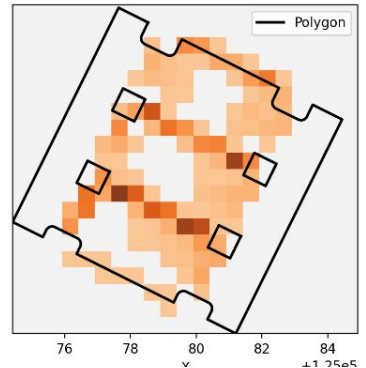
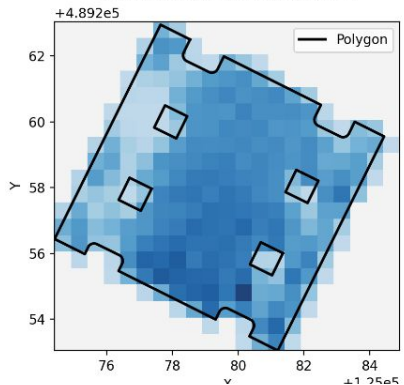
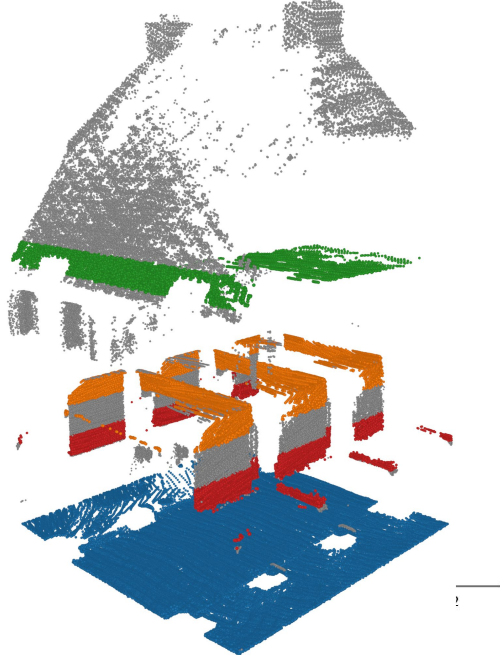
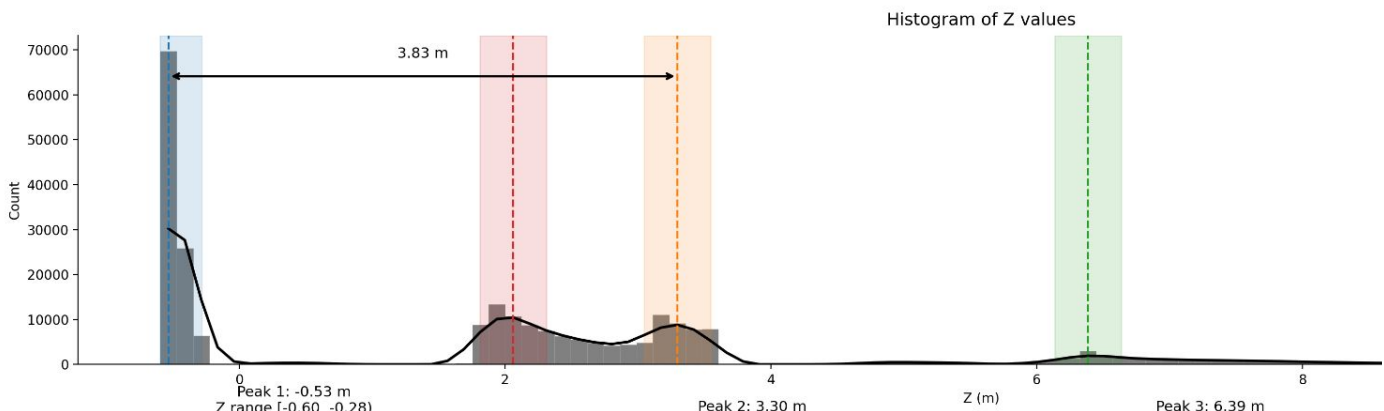


Histogram of Z values



Beemsterstraat

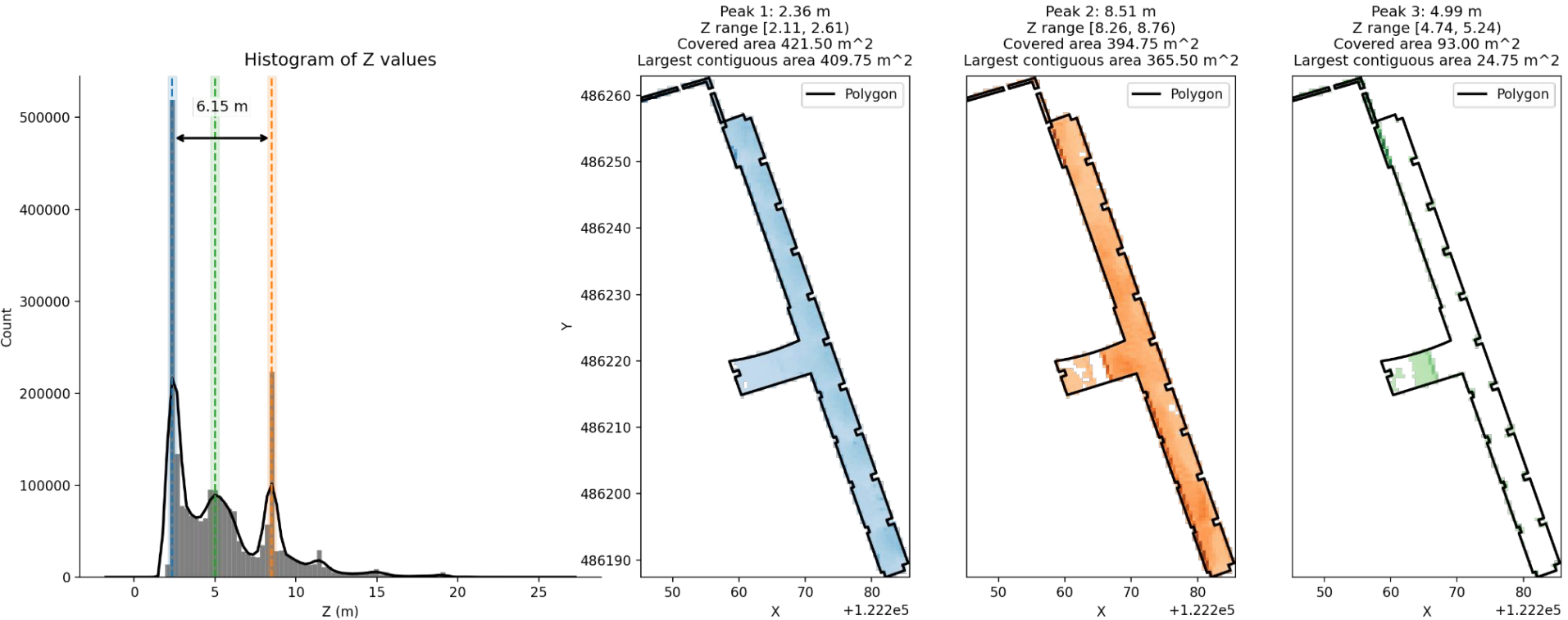
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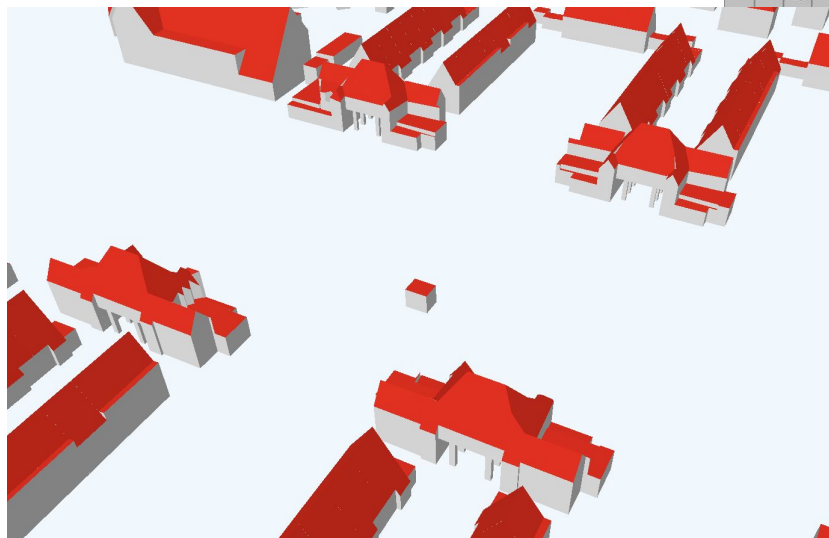
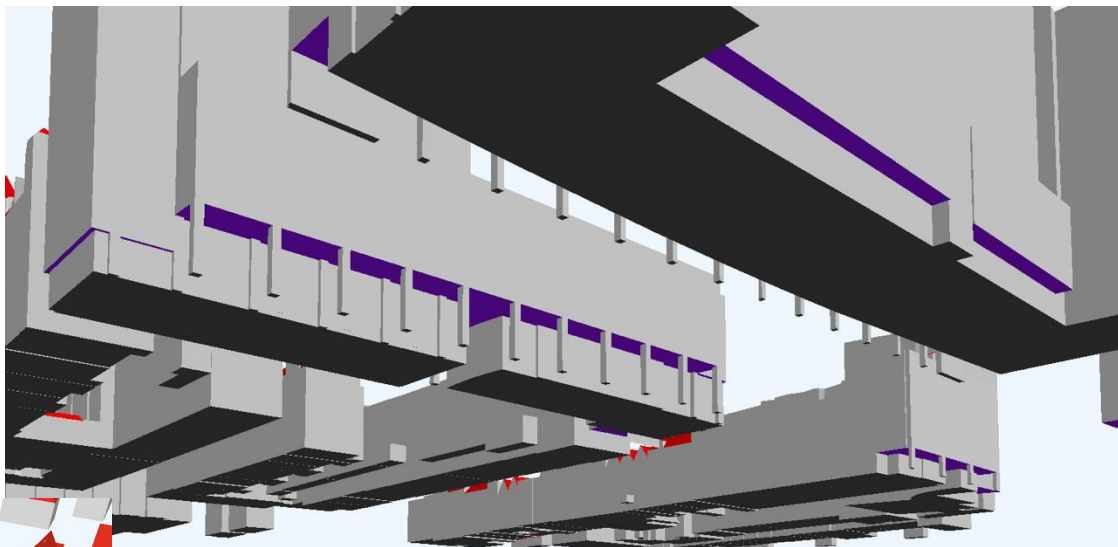
Weesperstraat



NL.IMBAG.Pand.0363100012170850



3D model resultaat



Current activities

- Trying to get more oblique imagery with good interior/exterior parameters
- Scale up to larger areas + iterative improvements
- Improve geometric validity of 3DBAG models

Innovatiebudget 2026

Projectplan Innovatiebudget 2026

- **'slim-actualiseren'** van 3DBAG, recentere en rijkerer 3D-gebouwmodellen door gebruik aanvullende gegevensbronnen + innovatieve algoritmes
- **Proof-of-concept-implementaties**, die de weg vrijmaken voor een toekomstige integratie in het 3DBAG-productieproces

Projectplan Innovatiebudget 2026

1. Verbeterde actualiteit door gebruik alternatieve bronnen
Op basis van data contributies door bv gemeentes
2. Verbeterd detail door puntenwolkfusie
3. Versiegeschiedenis op basis van mutatiedetectie
Maakt incrementele updates mogelijk
4. 'Tijdreizen': bekijk historische staat bebouwing
(waar data beschikbaar is)
5. Visualisatie in vernieuwde 3D-viewer



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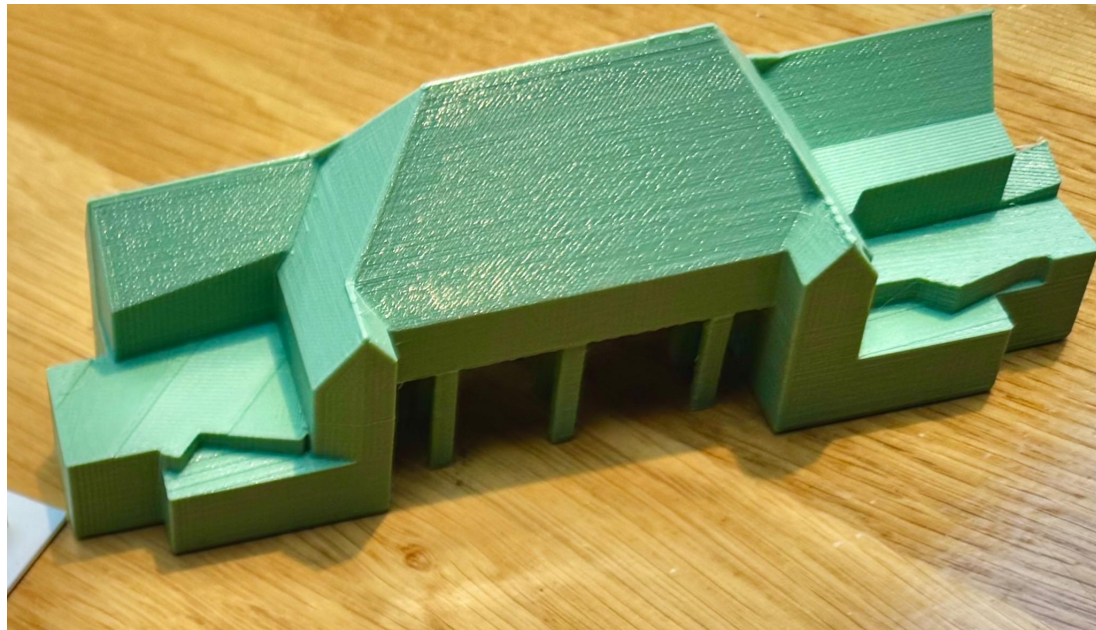


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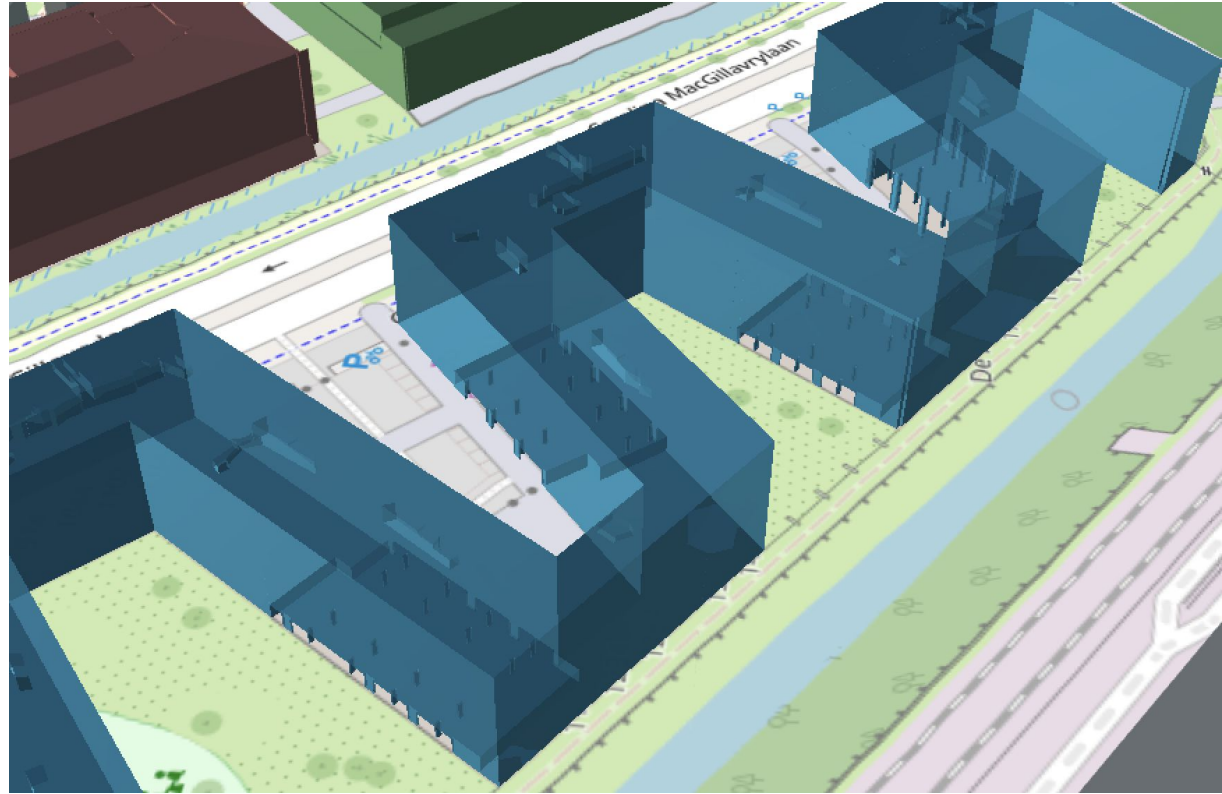
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Update, 11 mei 2026
Online



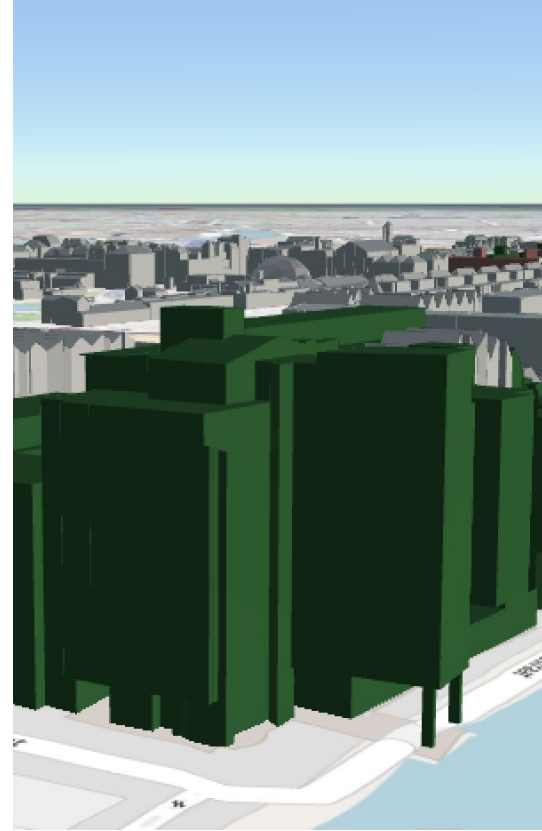
Inhoud

1. Status update
2. Demo
3. Over de hoogtebronnen
4. Volgende stappen
5. Volgende 3DBAG release



Status update

- ✓ Detectie + reconstructie onderdoorgangen voor heel NL
- ✓ Hoogte uit streetlidar voor heel Amsterdam
 - Met dank aan Wietse voor de data!
- ✓ Stage Juan voltooid (hoogte uit obliek)
- ✓ Implement border extension for 2D underpass polygons
- ✓ Algemene verbeteringen 2D + 3D delen van de pijplijn
- ✓ 1ste iteratie verbeteringen op basis van nationale run



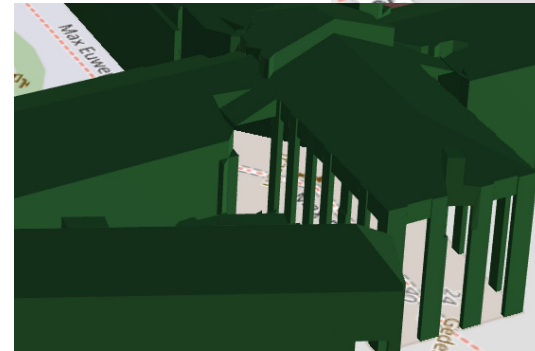
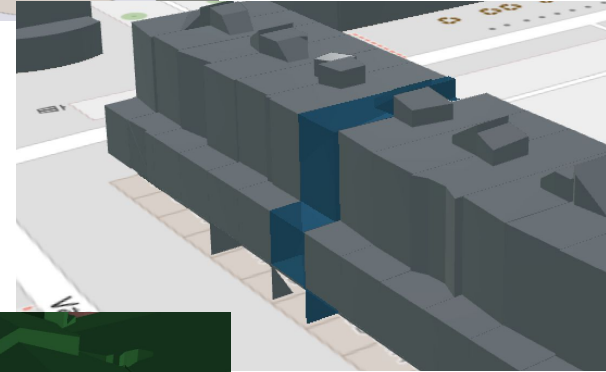
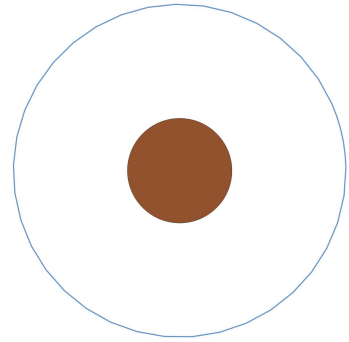
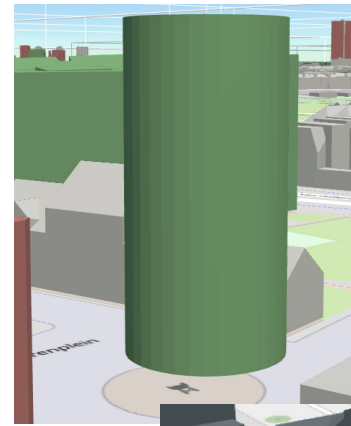
Demo

Voorlopige bevindingen

Type fouten:

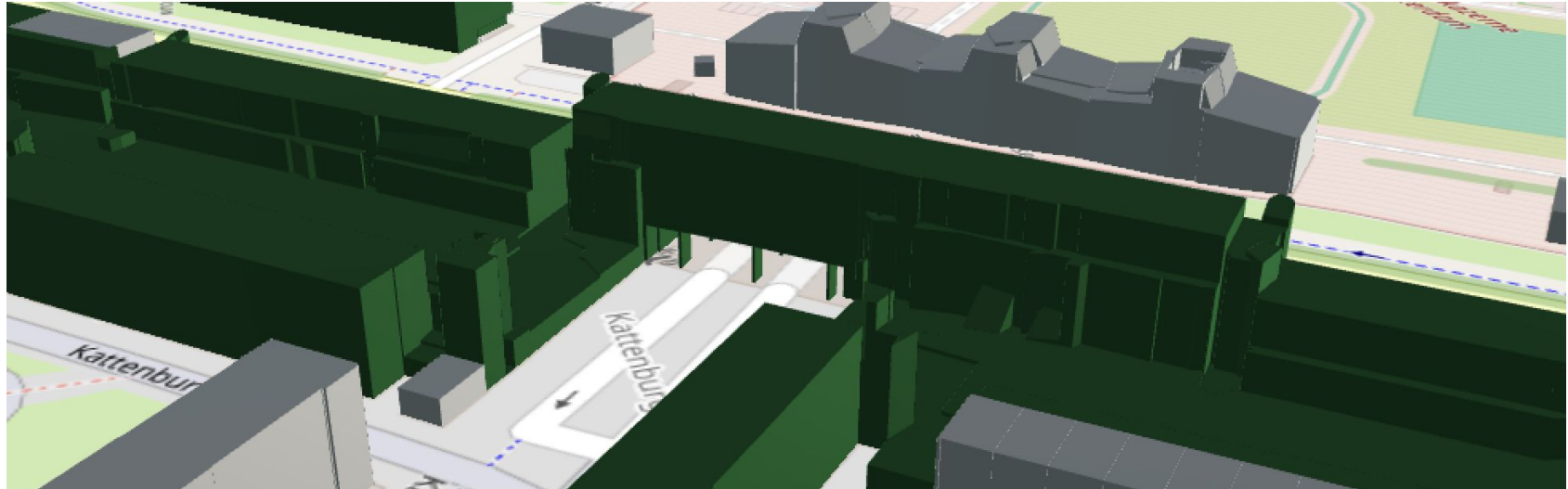
1. Geometrische verwerking 2D polygoon
 - a. Ontbrekende pilaren
 - b. Bepaling + extrusie van 'open' zijden
2. Geometrische validiteit 3DBAG modellen
 - a. Rode gebouwen in demo
 - b. Dit was voorzien in het voorstel
3. Hoogtebepaling uit straatlidar
 - a. Hoogte soms te hoog of te laag
 - b. Soms te weinig punten

Type 1, is reeds grotendeels gerepareerd.

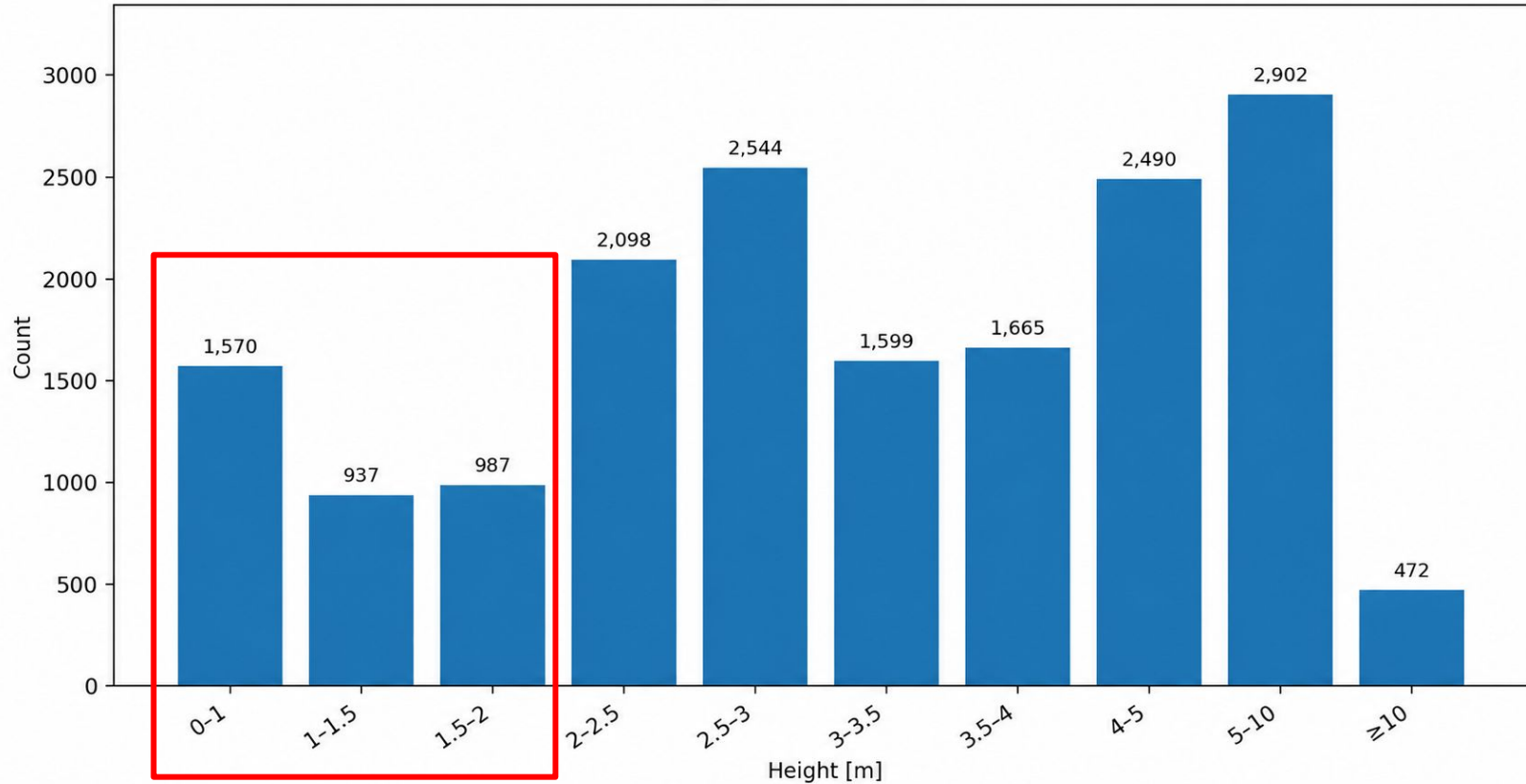


Hoogtebepaling uit streetlidar

- Met de Amsterdam data hebben we een heel mooi demo gebied
 - Incl toestemming gebruik voor 3DBAG
- Onze methode is snel en draait goed op bestaande hardware
- Huidige resultaten zijn bemoedigend, goed genoeg voor integratie 3DBAG



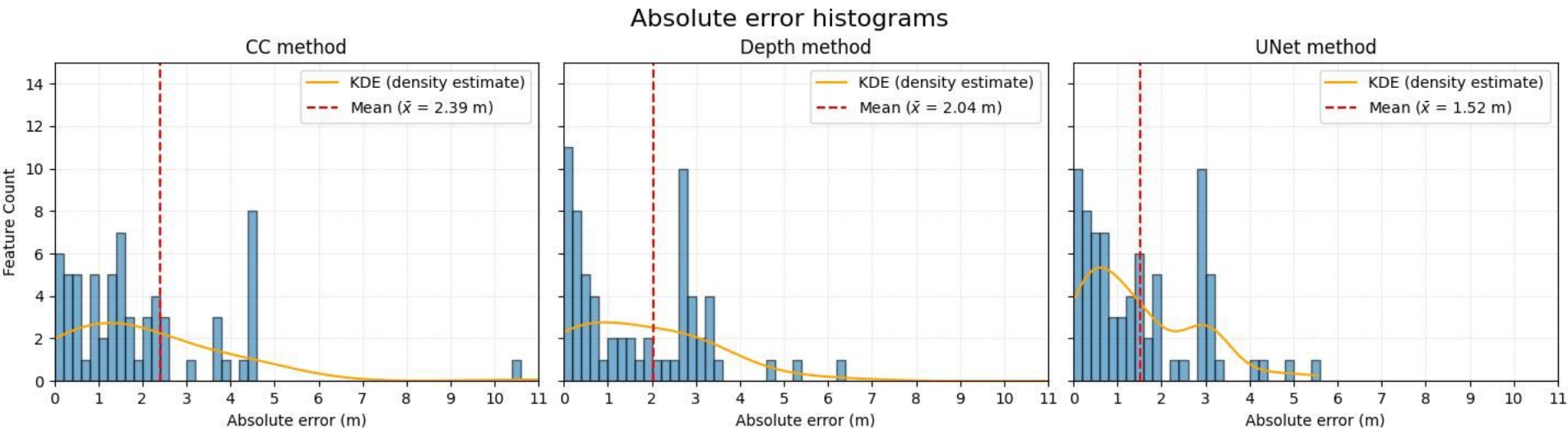
Hoogtes uit streetlidar (Amsterdam)



Hoogtebepaling uit oblieke beelden

- Stagair Juan heeft een [mooi rapport](#) opgeleverd
 - Vergelijking tussen 3 methodes, doorontwikkeling is nog nodig
 - Een interessante bevinding: 3D Rotterdam onderdoorgangen bevatten fouten

Na correctie 3D Rotterdam data



Hoogtebepaling uit oblieke beelden

- Methode is nog wel experimenteel + trager om te draaien
 - GPU Hardware is idealiter nodig
- Vereist hoge kwaliteit data (GSD + orientatie parameters)
- Data bronnen
 - Prorail heeft mooie open data, maar alleen rondom spoorwegen
 - Binnenkort (?): open data van HWH pilot Noord Nederland
 - Kavel10 heeft data opengesteld, maar is waarschijnlijk geen open data

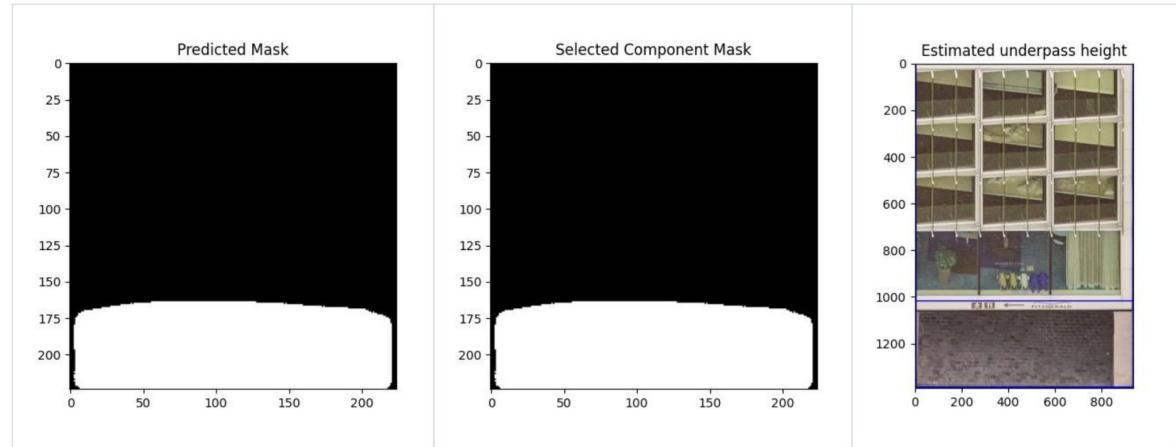
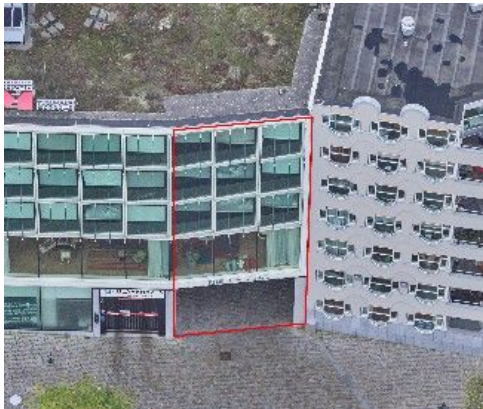
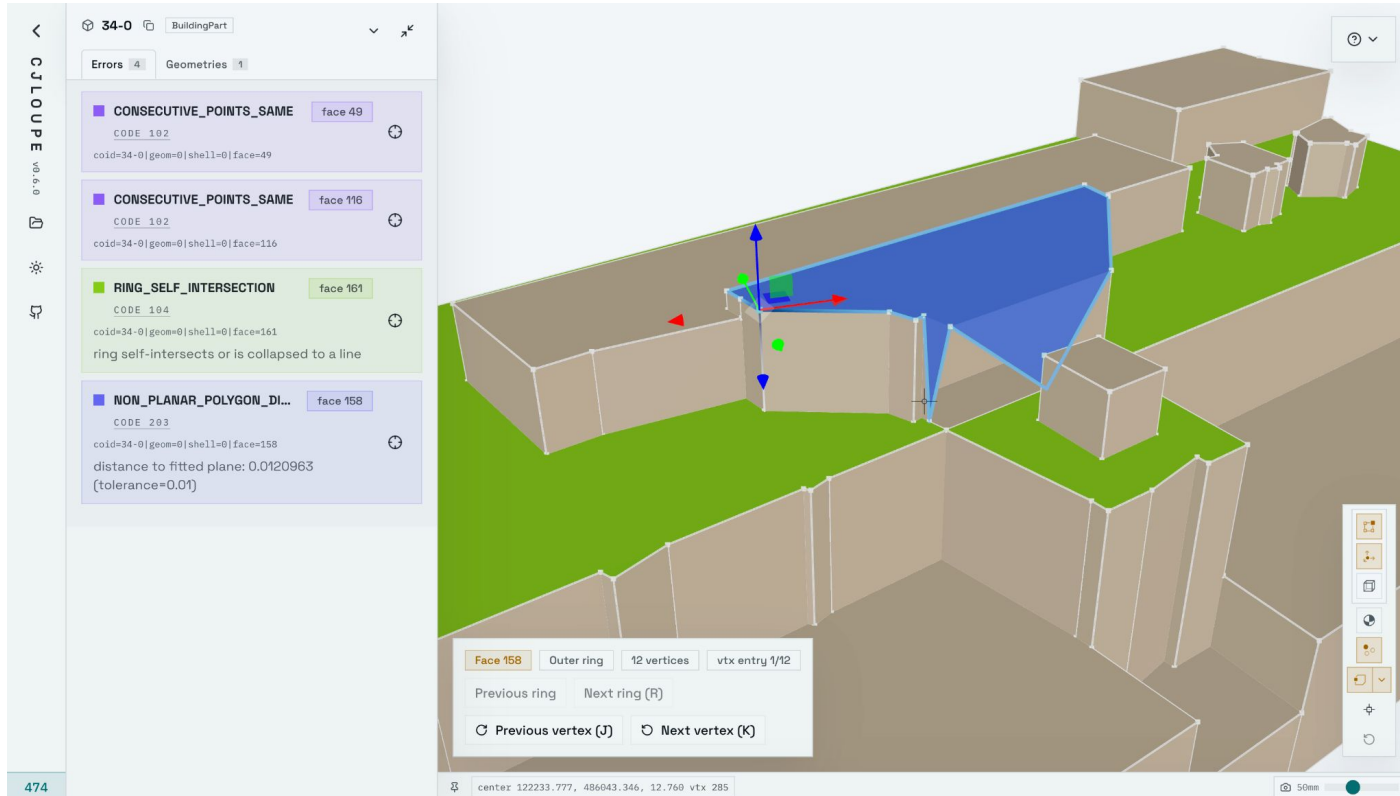


Figure 9. application of the U-Net model method.

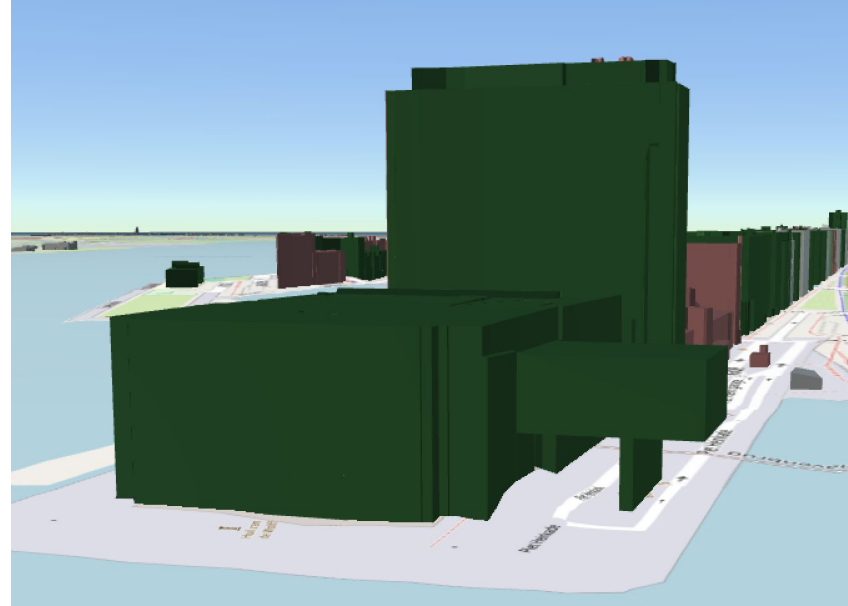
Verbeteren geometrische validiteit 3DBAG

Tussenstap: inspectie tool CityJSON geometrie (fouten op basis val3dity)



Volgende stappen

- Voorkomen van geometrische fouten in 3DBAG modellen
- Handmatige inspectie/validatie correctheid streetlidar hoogtes
- Iteratieve bug fixing
 - We zullen regelmatig de demo website updaten
 - We staan ook open voor feedback
- Integratie in 3DBAG pipeline



Volgende 3DBAG versie

- Huidige resultaten onderdoorgangen reeds beschikbaar als PoC
- Binnen innovatie project ook integratie in 3DBAG generatie pijplijn
- Meer werk dan voorzien voor integratie streetlidar data (Amsterdam)
- Voor 'officiële' nieuwe 3DBAG release zou ook mooi zijn:
 - Update op basis AHN6
 - Update van model voor schatting # bouwlagen
 - Bugs repareren
 - Algemene 3DBAG software verbeteringen en onderhoud
- Geschat budget hiervoor: 150 uren extra , ~22K

